

East Point Campus – "Jnanaprabha", Virgo Nagar Post, Bangalore-560049, Karnataka, India Website Contents

## Annexure -1

## Annexure -23

## Faculty Profile a brief Writeup with Maximum 150-200 words

Faculty	Dr.Praveen M P  Associate Professor – Department of Mechanical Engineering  East Point College of Engineering & Technology
	Profile*
	Dr.Praveen M P holds a Ph.D degree in Mechanical Engineering from Visvesvaraya Technological University, Belagavi, , M.Tech Degree from Visvesvaraya Technological University, Belagavi and B.E from Bangalore University, Bangalore.  He has worked at institution such as Acharya Institute of Technology, Bengaluru. He has worked at Various organizations such as SG Communications, Techno Globe, Logical Solutions and ABIBA Systems. A dedicated, passionate teacher with more than 15 years of experience in Academics and Industry. He has published publications in Peer reviewed and refereed Journals
	Publications - *
	Books chapters - *
	Journals - 11
	Patents - *
	Conferences - *
	Achievements / Awards / Recognitions – *



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## Annexure -2

Faculty	Dr.Praveen M P
racuity	Associate Professor – Department of Mechanical Engineering East Point College of Engineering & Technology
	Dr.Praveen M P holds a Ph.D degree in Mechanical Engineering
	from Visvesvaraya Technological University, Belagavi, , M.Tech Degree from Visvesvaraya Technological University, Belagavi and
	B.E from Bangalore University, Bangalore.  He has worked at institution such as Acharya Institute of
	Technology, Bengaluru. He has worked at Various organizations such as SG Communications, Techno Globe, Logical Solutions and
	ABIBA Systems.  A dedicated, passionate teacher with more than 15 years of experience in Academics and Industry. He has published
	publications in Peer reviewed and refereed Journals
V	Dublications /Journals
	Publications/Journals
	Design of harvesting mechanism for advanced remote-controlled coconut harvesting robot (arch-1)
	Techniques for inventory classification: A review
	Concept design and proto build of Roto parker for two wheeler
	New Frame Work For Robot Assisted Minimum Invasive Surgery
	Novel Approach for Inventory Planning Using OPAL and Some Neural Networks
	Evaluating unsupervised learning techniques for inventory classification
	Design and Fabrication of Multiutility Chair
	Design and Analysis of Pneumatic Pedal Pusher at Toyota Kirloskar Motors
	Design, Synthesis and Development of Adaptable Multi-postured Chair for ATM Security Personnel
	Visual Data Mining: A case study in Thermal Power Plant
	Fabrication of Advanced Remote-Controlled Coconut Harvesting Robot (ARCH-1) Incorporating Rapid Prototyping Technology